# Human-Robot Interaction

Module 5: Emotion

Lecture 1: The roles of emotions in interaction

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# Topics

- Emotion, mood, and affect
- Human emotions
- Incorrectly interpreting emotion

### The roles of emotions in interaction

- Taking emotions into account in the design of a robot can help improve the intuitiveness of the human-robot interaction
- Emotions can motivate and modulate behavior
  - They are a necessary component of human cognition and human behavior
- Social robots are often designed
  - To interpret human emotion
  - To express emotions
  - To have some some form of synthetic emotion drive their behavior

### Emotions arise as an appraisal of a person's situation

- Prepare the body for behavioral responses
- Help in decision-making
- Facilitate interpersonal interaction
- Evoke empathetic responses from others:
  emotions help modulate the behaviors of others in an interaction
- Triggered by an identifiable source
- Often externalized and directed at a specific object or person

### Moods are more diffuse and internal

- Often lack a clear cause and object
- Are the result of an interaction between
  - Environmental
  - Incidental, and
  - Cognitive processes

Affect is the term used to encompass all forms of emotion and mood

- Quick, sub-conscious emotional responses triggered by external circumstances
- ...
- Longer-lasting moods

Affect makes a distinction between **emotion** and **mood** 

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### Emotions are a universal communication channel

Communication our internal affective state to others

- 1. Convey information about the agent and its future actions (look of anger, fear, desire, ...)
- 2. Convey information about the environment (look of fear or peace, ...)

In both cases, emotion provides an incentive for others to take action

### Emotions are a universal communication channel

#### Successful communication of emotions

- Enhances the chances of survival
- Enhances social bonds
- Minimizes the changes of social rejection and social interpersonal physical aggression

## **Human Emotions**

## There are many different emotions

- Anger
- Sadness
- Happiness
- Love
- Mildness
- Pride
- Relief
- Satisfaction
- Sensory pleasure
- Shame
- ..

14 according to Aristotle15 according to Ekman (1999)6 basic emotions according to Ekman & Friesen (1975)anger, surprise, disgust, enjoyment, fear, and sadness.

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## **Human Emotions**

## Primary vs. Secondary Emotions

- No consensus on whether this is a valid distinction or, if it is, which to assign to which category
- Possible primary emotions are quick, gut-level responses:
  - Amusement
  - Anger
  - Surprise
  - Disgust
  - Fear
- Possible secondary emotions are reflective and differ across cultures:
  - Pride
  - Remorse
  - Guilt

## **Human Emotions**

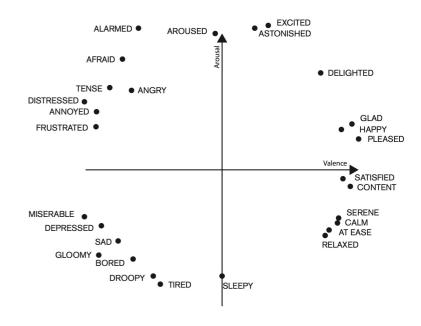
#### Alternative view:

Emotions are the cognitive interpretations of sensations that result from two independent neurophysiological systems

- Arousal
- Valence

This model holds across many cultures and languages

But it does not accommodate all affective states



Russel's circumplex model of affect (Russel 1980)

# Incorrectly Interpreting Emotions

- Misinterpreting emotions can have serious consequences giving rise to misunderstandings
- Some people have great difficult interpreting displays of emotion
  - People on the Autism Spectrum Disorder (ASD)
  - Cannot understand the affective needs of the interaction partners
  - Often resulting in inappropriate responses
- Some people are physically incapable of expressing emotion
  - e.g. people with impaired facial muscle control after a stoke
  - Significantly impacting ability to provide or respond to emotional cues during interaction

# Incorrectly Interpreting Emotions

Social interactions with robots may be more difficult if the robot is unable to express and interpret emotional states

# Reading

Bartneck, C., Belpaeme, T., Eyssel, F., Kanda, T., Keijsers, M., Sabanovic, S. (2020). Human-Robot Interaction - An Introduction, Cambridge University Press.

Chapter 8 – Emotion, pp. 114-117.