

Robotics: Principles and Practice

Module 1: Introduction and Robot Components

Lecture 1: What is a robot? Types of robot. The many areas of robotics.

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www.vernon.eu

What is a Robot?

What is a Robot?

"A robot is an **autonomous system** ← Not teleoperated (self-controlled & has controllers)
which exists in the **physical world**, ← Subject to the physical laws (has a physical body)
can **sense** its environment, ← Estimate the state of the world (uses sensors)
and can **act** on it ← Physically affect the world (uses actuators & effectors)
to achieve some **goals**" ← Purposeful, useful, possibly intelligent behaviour

M. Mataric, The Robotics Primer, MIT Press, 2007.

Types of Robot

ROBOTS

YOUR GUIDE TO THE WORLD OF ROBOTICS

[Home](#)
[Robots](#)
[News](#)
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Source: <https://robots.ieee.org/robots/>

ALL ROBOTS

SORT ROBOTS

ROBOT RANKINGS

Name (A to Z)

Size (Smallest to Largest)

Date (Newest to Oldest)

Type ▾

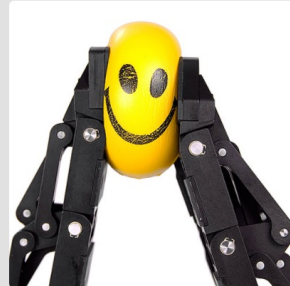
Country ▾

Shuffle!

- Humanoids
- Consumer
- Drones
- Entertainment
- Education
- Research
- Medical
- Exoskeletons
- Disaster Response
- Service & Industrial
- Aerospace
- Underwater
- Military & Security
- Telepresence
- Self-Driving Cars



ACM-R5H



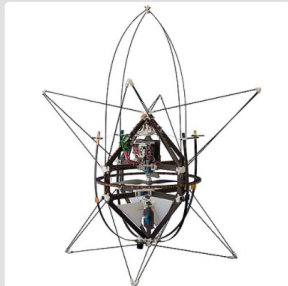
Adaptive Gripper



Aibo



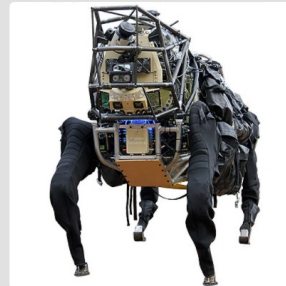
AILA



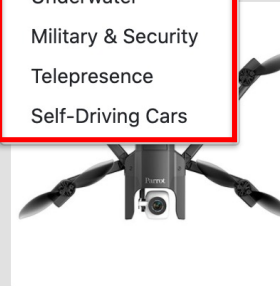
AirBurr



Albert Hubo



AlphaDog



Anafi



Anki Drive

Types of Robot

Humanoids Research




Armar

Armar is a robot created to be a helper in industrial environments. Its humanoid form lets it use human tools like power drills and hammers. Earlier versions were home helpers that could clean tables and load the dishwasher.

CREATOR

Karlsruhe Institute of Technology [↗](#)

COUNTRY

Germany 

YEAR

2017

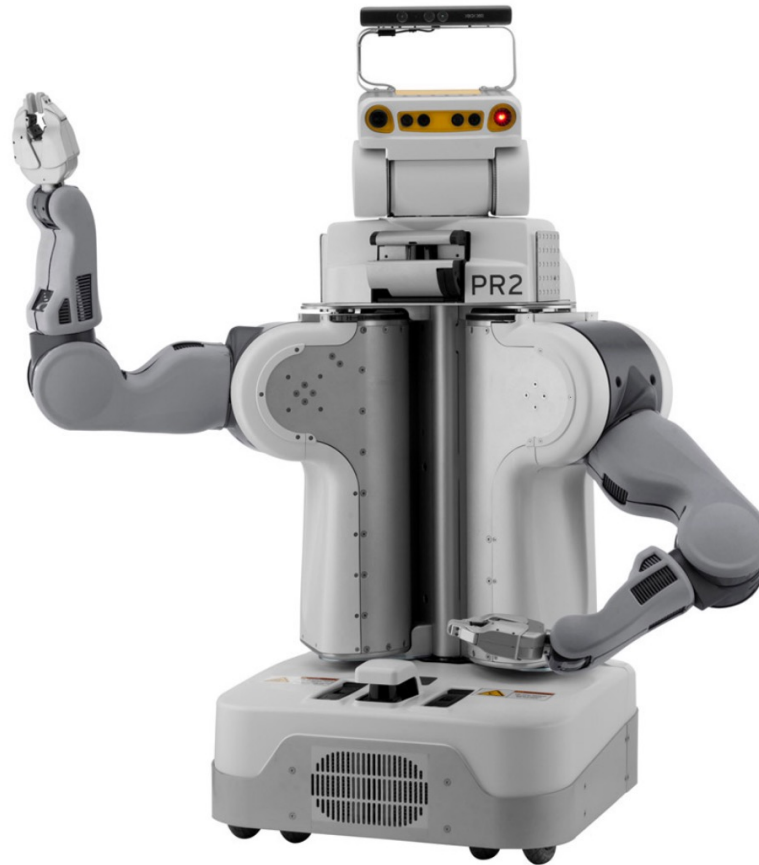
TYPE

Humanoids, Research

Source: <https://robots.ieee.org/robots/armar/>

Types of Robot

Humanoids Research




PR2

The PR2 is one of the most advanced research robots ever built. Its powerful hardware and software systems let it do things like clean up tables, fold towels, and fetch you drinks from the fridge.

CREATOR

Willow Garage [↗](#)

COUNTRY

United States 

YEAR

2010

TYPE

Research, Humanoids

Source: <https://robots.ieee.org/robots/pr2/>

Types of Robot

Humanoids
Consumer
Entertainment



Pepper


Pepper is a friendly humanoid designed to be a companion in the home and help customers at retail stores. It talks, gesticulates, and seems determined to make everyone smile.

CREATOR

SoftBank Robotics [↗](#)

(originally created by Aldebaran Robotics, acquired by SoftBank in 2015)

COUNTRY

Japan 

YEAR

2014

TYPE

Humanoids, Consumer, Entertainment

Source: <https://robots.ieee.org/robots/pepper/>

Types of Robot

Humanoids
Research
Education



Nao


Nao is a small humanoid robot designed to interact with people. It's packed with sensors (and character) and it can walk, dance, speak, and recognize faces and objects. Now in its sixth generation, it is used in research, education, and healthcare all over the world.

CREATOR

SoftBank Robotics [↗](#)

(originally created by Aldebaran Robotics, acquired by SoftBank in 2015)

COUNTRY

France 

YEAR

2008

TYPE

Humanoids, Research, Education

Source: <https://robots.ieee.org/robots/nao/>

Types of Robot

Humanoids Research




HRP-4

HRP-4 is one of the world's most advanced humanoids, the culmination of a decade of R&D. It's designed to collaborate with humans and can perform remarkably natural, human-like movements.

CREATOR

Kawada Industries and AIST [↗](#)

COUNTRY

Japan 

YEAR

2010

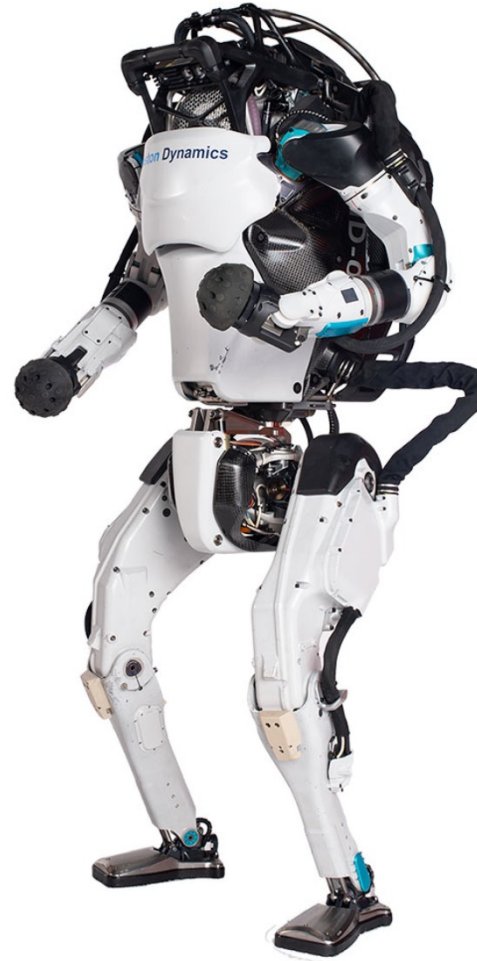
TYPE

Humanoids, Research

Source: <https://robots.ieee.org/robots/hrp4/>

Types of Robot

Humanoids
Industrial




Atlas

Atlas is the most agile humanoid in existence. It uses whole-body skills to move quickly and balance dynamically. It can lift and carry objects like boxes and crates, but its favorite tricks are running, jumping, and doing backflips.

CREATOR

Boston Dynamics [↗](#)

COUNTRY

United States 

YEAR

2016

TYPE

Humanoids, Industrial

Source: <https://robots.ieee.org/robots/atlas2016/>

A large industrial workshop with yellow overhead cranes, toolboxes, and a large log on the floor. The scene is brightly lit with fluorescent lights. In the foreground, a large, rough-textured log lies horizontally on the floor. To the right, there are several black toolboxes with silver handles. In the background, there are yellow overhead cranes and various industrial equipment. A sign on the wall reads "NOT AN EXIT" and another says "CAUTION EYE PROTECTION".

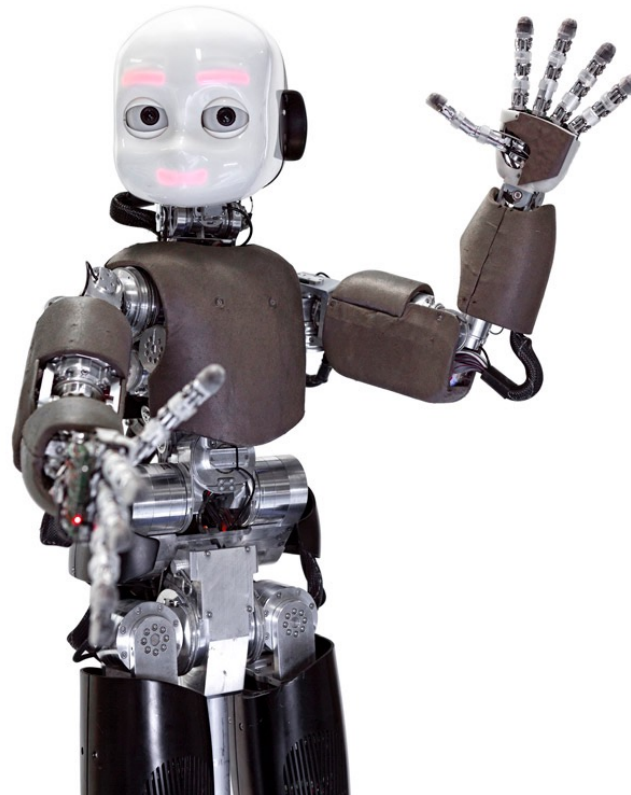
Video

<https://robots.ieee.org/robots/atlas2016/?gallery=video5>

Boston Dynamics

Types of Robot

Humanoids Research




iCub

iCub is a child-size humanoid robot capable of crawling, grasping objects, and interacting with people. It's designed as an open source platform for research in robotics, AI, and cognitive science.

CREATOR

RoboCub Consortium and IIT 

COUNTRY

Italy 

YEAR

2004

TYPE

Humanoids, Research

Source: <https://robots.ieee.org/robots/icub/>

Video

<https://robots.ieee.org/robots/icub/?gallery=video1>

Types of Robot

Consumer



Roomba

Roomba is an autonomous vacuum and one of the most popular consumer robots in existence. It navigates around clutter and under furniture cleaning your floors, and returns to its charging dock when finished.

CREATOR

iRobot 

COUNTRY

United States 

YEAR

2002

TYPE

Consumer

Source: <https://robots.ieee.org/robots/roomba/>

Video

<https://robots.ieee.org/robots/roomba/?gallery=video2>

Types of Robot

Education



Roomba

Roomba is an autonomous vacuum and one of the most popular consumer robots in existence. It navigates around clutter and under furniture cleaning your floors, and returns to its charging dock when finished.

CREATOR

iRobot 

COUNTRY

United States 

YEAR

2002

TYPE

Consumer

Source: <https://robots.ieee.org/robots/roomba/>

Types of Robot

Consumer
Research
Education




TurtleBot

TurtleBot is a low-cost personal robot designed for hobbyists and researchers. It's open source, runs the ROS operating system, and combines a netbook with a Kinect 3D sensor and a mobile base.

CREATOR

Willow Garage [↗](#)

COUNTRY

United States 

YEAR

2011

TYPE

Consumer, Research, Education

Source: <https://robots.ieee.org/robots/turtlebot/>

Video

<https://robots.ieee.org/robots/turtlebot/?gallery=video1>

Types of Robot

Drones
Military & Security



Global Hawk

The Global Hawk is an unmanned aerial vehicle that's used for high-altitude, long-duration surveillance. You tell it what to do, and it can take off, fly, spy, and return without any human input.

CREATOR

Northrop Grumman [↗](#)

COUNTRY

United States 

YEAR

2001

TYPE

Aerospace, Military & Security, Drones

Source: <https://robots.ieee.org/robots/globalhawk/>

Types of Robot

Drones
Medical



Zipline

Zipline is an autonomous fixed-wing aircraft drone used to carry blood and medicine from a distribution center to wherever it's needed. It can launch within minutes, and travel in any weather.

CREATOR

Zipline [↗](#)

COUNTRY

United States 

YEAR

2016

TYPE

Drones, Medical

Source: <https://robots.ieee.org/robots/zipline/>

A close-up photograph of a laboratory or medical setting. A person wearing blue nitrile gloves is using a black and white pipette to transfer a liquid into a red and white bag. The bag is resting on a digital scale, which has a display showing '0.140'. The bag has a label with the word 'zipline' and a barcode. The background is slightly blurred, showing a white wall and some equipment.

Video

http://www.vernon.eu/videos/Zipline_hero.mp4

An aerial photograph of a densely populated hillside. A road runs horizontally across the middle of the frame, and a river flows along the bottom edge. The hillside is covered with numerous small, colorful buildings, and the surrounding area is green with vegetation.

Video

<https://www.youtube.com/watch?v=QWglZKVP26c>

Video

http://www.vernon.eu/videos/Zipline_drop.mp4



Types of Robot

Entertainment
Consumer



Aibo

Aibo is a friendly robotic dog whose personality and behavior evolves over time. It can recognize its owner's face, detect smiles and words of praise, and learn new tricks. And of course, it loves to be petted.

CREATOR

Sony 

COUNTRY

Japan 

YEAR

2018

TYPE

Consumer, Entertainment

Source: <https://robots.ieee.org/robots/aibo2018/>

Video

<https://www.youtube.com/watch?v=5ifwGc-0mAY>

Types of Robot

Industrial




Picker Robots

Picker Robots are mobile machines designed to autonomously retrieve and carry products in a warehouse. The robots are directed through AI-powered software that identifies the most efficient paths for them to pick, replenish, return, and count goods.

CREATOR

inVia Robotics [↗](#)

COUNTRY

United States 

YEAR

2015

TYPE

Industrial

Source: <https://robots.ieee.org/robots/invia/>

A photograph of a warehouse interior. On the right side, there are tall metal shelving units filled with numerous cardboard boxes, many of which have white labels. A red mobile robot is positioned in the center of the aisle, facing away from the camera. The floor is a light-colored concrete. On the left, there is a plain white wall. The scene is lit by overhead fluorescent lights.

Video

<https://robots.ieee.org/robots/invia/?gallery=video5>

Types of Robot

Industrial




Freight

Freight is an autonomous mobile base for use in warehouses to transport materials from point A to point B. The robot platforms come in three zippy flavors – 100, 500 and 1500, all of which represent the payload it can handle in kilograms.

CREATOR

Fetch Robotics [↗](#)

COUNTRY

United States 

YEAR

2014

TYPE

Industrial

Source: <https://robots.ieee.org/robots/freight/>

Types of Robot


Industrial




Sawyer

Sawyer is an industrial collaborative robot designed to help out with manufacturing tasks and work alongside humans. You can teach it new tasks by demonstrating what to do using the robot's own arm.

CREATOR

Rethink Robotics 

COUNTRY

United States 

YEAR

2015

TYPE

Industrial

Source: <https://robots.ieee.org/robots/sawyer/>



video

<https://robots.ieee.org/robots/sawyer/?gallery=video1>

Types of Robot

Industrial



Meca500

Meca500 is the world's smallest, most compact six-axis industrial robot arm. It's also one of the most precise. And with an embedded controller it can easily be transported and set up in confined spaces.

CREATOR

Mecademic 

COUNTRY

Canada 

YEAR

2015

TYPE

Industrial

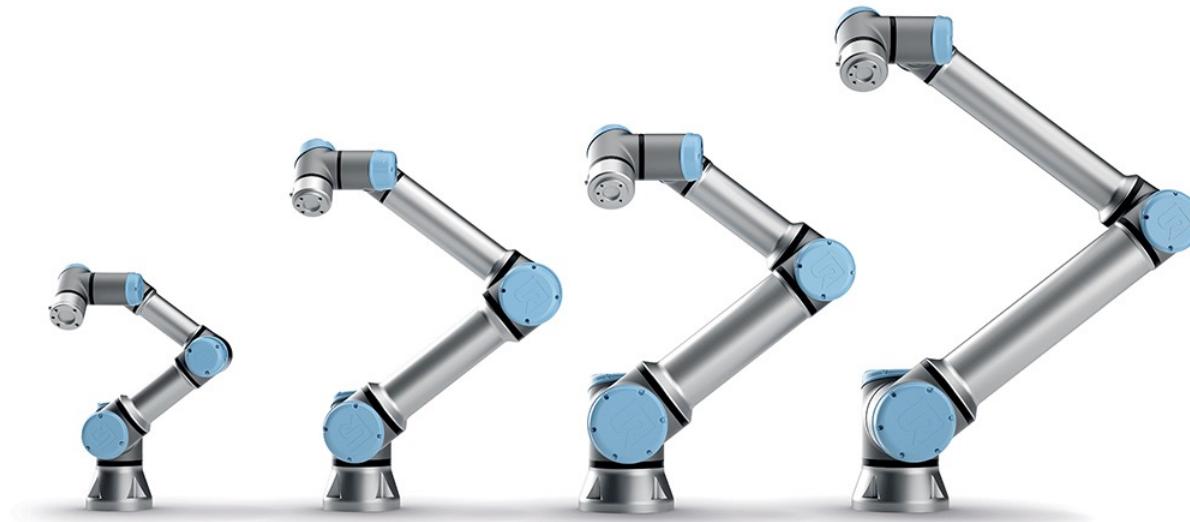
Source: <https://robots.ieee.org/robots/meca/>

Video

<https://robots.ieee.org/robots/meca500/?gallery=video1>

Types of Robot

Industrial



UR

Universal Robots cobots are versatile, lightweight collaborative robotic arms designed to work safely alongside humans. Users program it through an intuitive touch-screen interface and by positioning the robot with their hands.

CREATOR

Universal Robots [↗](#)

COUNTRY

Denmark 

YEAR

2008

TYPE

Industrial

Source: <https://robots.ieee.org/robots/ur/>

Types of Robot

Research
Industrial



Shadow Hand

The Shadow Dexterous Hand is one of the most advanced robot hands in the world. It's designed to replicate as much of the functionality, dimensions, and range of motion of the human hand as possible.

CREATOR

Shadow Robot Company [↗](#)

COUNTRY

United Kingdom 

YEAR

2004

TYPE

Industrial, Telepresence, Research

Source: <https://robots.ieee.org/robots/shadow/>

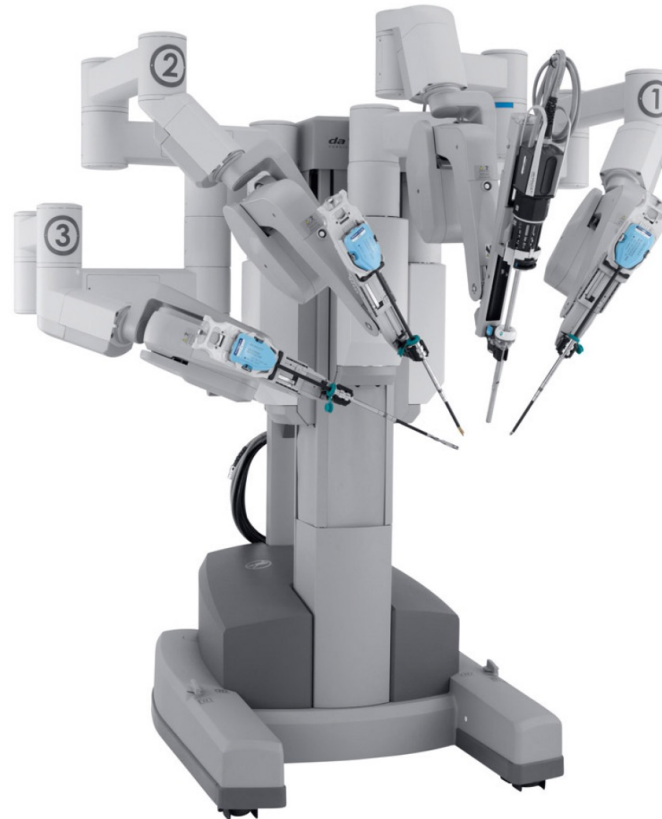
A Shadow Hand II robotic arm is positioned in a kitchen-like environment. In the foreground, a wooden tray holds a coffee cup, a small black object, and a tablet displaying a piano keyboard. To the right of the tray are two black boxes containing colorful cards. The background shows a counter with various bottles and a sink.

Video

<https://robots.ieee.org/robots/shadow/?gallery=video4>

Types of Robot

Medical



Da Vinci

The da Vinci is a surgical robot designed for minimally invasive procedures. It has four arms equipped with surgical instruments and cameras that a physician controls remotely from a console.

CREATOR

Intuitive Surgical [↗](#)

COUNTRY

United States 

YEAR

1999

TYPE

Medical

Source: <https://robots.ieee.org/robots/davinci/>

THE DA VINCI SURGICAL SYSTEM



Patient Side Manipulators: robotic arms teleoperated by the Master Tool Manipulators, they mount the surgical tools.

Endoscopic Camera Manipulator: robotic arm that is also teleoperated by the Master Tool Manipulators, it holds the endoscope.



Video

<https://www.youtube.com/watch?v=961E6Nx9Pok>

Types of Robot

Consumer Telepresence




Beam

Beam is a telepresence robotic system that can "teleport" you to a remote location, allowing you to move around and interact with people. It is easy to drive and has a large display to improve face-to-face, or screen-to-face, communication.

CREATOR

Suitable Technologies [↗](#)

COUNTRY

United States 

YEAR

2011

TYPE

Telepresence, Consumer

Source: <https://robots.ieee.org/robots/beam/>

Types of Robot

Autonomous Vehicle Research



Boss

Boss is the world's smartest Chevy Tahoe. In 2007, it won the DARPA Urban Challenge for autonomous vehicles, taking home a \$2 million prize for not breaking any traffic laws or running anyone over.

CREATOR

Carnegie Mellon University [↗](#)

COUNTRY

United States 

YEAR

2007

TYPE

Autonomous Vehicle, Research

Source: <https://robots.ieee.org/robots/boss/>

Types of Robot

Autonomous Vehicle Research



Google Self-Driving Car

Google's self-driving car is a modified Toyota Prius that can autonomously drive in city traffic and on highways. The goal is developing technology to reduce traffic accidents and increase road efficiency.

CREATOR

Google 

COUNTRY

United States 

YEAR

2010

TYPE

Autonomous Vehicle, Research

Source: <https://robots.ieee.org/robots/beam/>

Types of Robot

Industrial
Research
Disaster Response



ANYmal

ANYmal is a rugged, autonomous four-legged robot designed for inspection and manipulation tasks. It uses sensors to scan the terrain and avoid obstacles, and can operate in rain, snow, wind, waterlogged rooms, and dusty environments.

CREATOR

ETH Zurich and ANYbotics [↗](#)

COUNTRY

Switzerland 

YEAR

2016

TYPE

Industrial, Research, Disaster Response

Source: <https://robots.ieee.org/robots/anymal/>

Types of Robot

Industrial Research



Spot

Spot is a compact, nimble four-legged robot that can trot around your office, home, or outdoors. It can map its environment, sense and avoid obstacles, climb stairs, and open doors. It can also fetch you a drink.

CREATOR

Boston Dynamics [↗](#)

COUNTRY

United States 

YEAR

2016

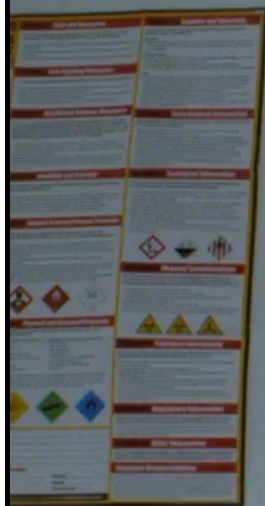
TYPE

Industrial, Research

Source: <https://robots.ieee.org/robots/spotmini/>

Video

<https://robots.ieee.org/robots/spotmini/?gallery=video1>



BOSTON DYNAMICS — SEPTEMBER 2019

DATE	MONITOR	VIDEO	REVISIONS	REVISIONS	REVISIONS	REVISIONS
1	1	1	1	1	1	1
2	2	2	2	2	2	2
3	3	3	3	3	3	3
4	4	4	4	4	4	4
5	5	5	5	5	5	5
6	6	6	6	6	6	6
7	7	7	7	7	7	7
8	8	8	8	8	8	8
9	9	9	9	9	9	9
10	10	10	10	10	10	10
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14	14	14	14	14	14	14
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27	27	27	27	27	27	27
28	28	28	28	28	28	28
29	29	29	29	29	29	29
30	30	30	30	30	30	30



Types of Robot

Military & Security Research



AlphaDog

AlphaDog is a quadruped robot the size of a mule (a big, mean mule). It's powered by a hydraulic actuation system and is designed to assist soldiers in carrying heavy gear over rough terrain.

CREATOR

Boston Dynamics [↗](#)

COUNTRY

United States 

YEAR

2011

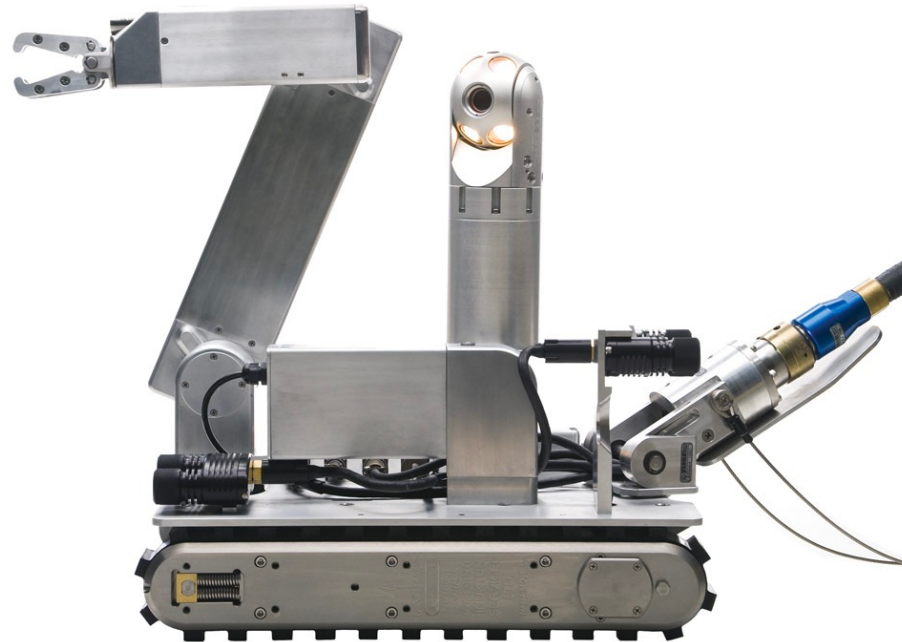
TYPE

Military & Security, Research

Source: <https://robots.ieee.org/robots/alphadog/>

Types of Robot

Industrial
Military & Security
Disaster Response




Versatrax

Versatrax 450 TTC is a mobile robot designed for hazardous environments. It allows users to locate, inspect, and safely remove dangerous materials from any site faster than by conventional means.

CREATOR

Inuktun Services [↗](#)

COUNTRY

Canada 

YEAR

2012

TYPE

Industrial, Military & Security, Disaster Response

Source: <https://robots.ieee.org/robots/inuktun/>

Types of Robot

Military & Security Disaster Response




Kobra

Kobra is a rugged, remote control robot designed to search for explosives and carry out reconnaissance missions. It rolls on tank-like treads, and its manipulator arm can lift heavy payloads.

CREATOR

Endeavor Robotics [↗](#)
(Originally created by iRobot)

COUNTRY

United States 

YEAR

2011

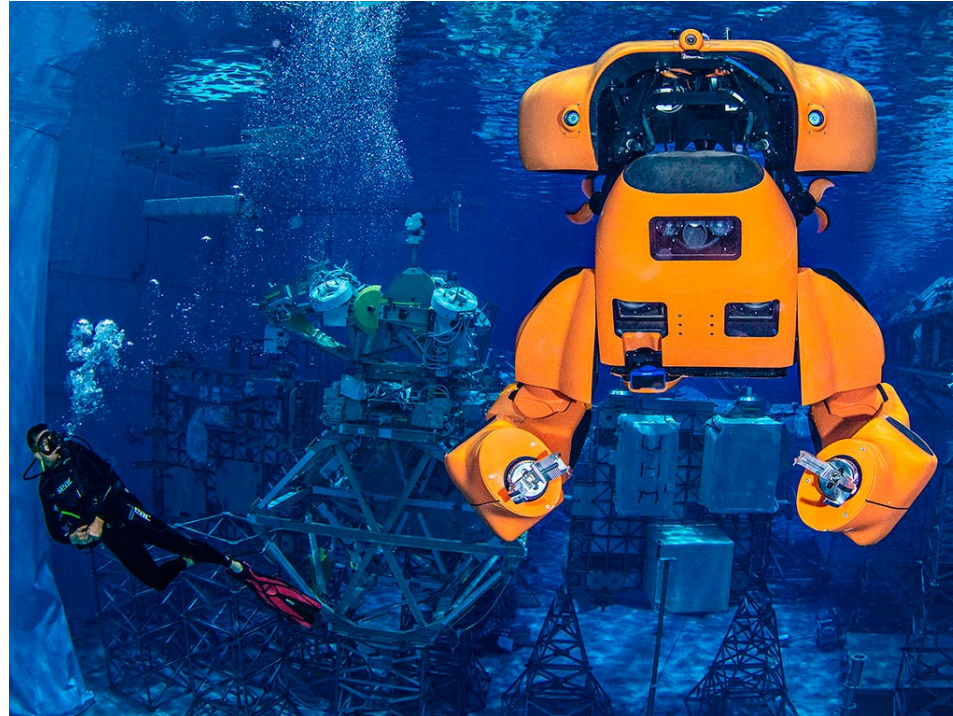
TYPE

Military & Security, Disaster Response

Source: <https://robots.ieee.org/robots/kobra/>

Types of Robot

Underwater
Industrial



Aquanaut

Aquanaut is an unmanned underwater vehicle that can transform itself from a nimble submarine designed for long-distance cruising into a half-humanoid robot capable of carrying out complex manipulation tasks. It can inspect subsea oil and gas infrastructure, operate valves, and use tools.

CREATOR

Houston Mechatronics Inc. [↗](#)

COUNTRY

United States 

YEAR

2019

TYPE

Underwater, Industrial

Source: <https://robots.ieee.org/robots/aquanaut/>

Types of Robot

Research



Salamandra robotica II

Salamandra robotica II is an amphibious robot inspired by the salamander's anatomy and nervous system. It's used to study robot locomotion and test neurobiological models in real environments.

CREATOR

Biorobotics Laboratory at EPFL [↗](#)

COUNTRY

Switzerland 

YEAR

2012

TYPE

Research

Source: <https://robots.ieee.org/robots/salamandra/>

A group of people, mostly men, are gathered around a large, shallow, rectangular tank. Inside the tank, a small, yellow and black salamander-like robot is visible. The people are looking at the robot with interest. Some are holding cameras or smartphones, suggesting they are taking photos or videos. The setting appears to be a conference or exhibition hall, with other people and displays visible in the background. The word "Video" is overlaid in large white text in the center of the image.

Video

<https://robots.ieee.org/robots/salamandra/?gallery=video4>

The Many Areas of Robotics



Technical Committees

Aerial Robotics and Unmanned Aerial Vehicles
Agricultural Robotics and Automation
Algorithms for Planning and Control of Robot Motion
Automation in Health Care Management
Automation in Logistics

Autonomous Ground Vehicles and Intelligent Transportation Systems
Bio Robotics
Cognitive Robotics
Collaborative Automation for Flexible Manufacturing
Computer & Robot Vision

Cyborg & Bionic Systems
Digital Manufacturing and Human-Centered Automation
Energy, Environment, and Safety Issues in Robotics and Automation
Haptics
Human Movement Understanding

Human-Robot Interaction & Coordination
Humanoid Robotics
Marine Robotics
Mechanisms and Design
Micro/Nano Robotics and Automation

Mobile Manipulation
Model-Based Optimization for Robotics
Multi-Robot Systems
Neuro-Robotics Systems
Performance Evaluation & Benchmarking of Robotic and Automation Systems

Rehabilitation and Assistive Robotics
RoboCup
Robot Ethics
Robot Learning
Robotic Hands, Grasping and Manipulation

Robotics and Automation in Nuclear Facilities
Robotics Research for Practicality
Safety, Security and Rescue Robotics
Semiconductor Manufacturing Automation
Smart Buildings

Soft Robotics
Software Engineering for Robotics and Automation
Space Robotics
Surgical Robotics
Sustainable Production Automation

Telerobotics

Verification of Autonomous Systems
Wearable Robotics
Whole-Body Control

<https://www.ieee-ras.org/technical-committees>

Reading

D. Vernon, "Robotics and Artificial Intelligence in Africa", IEEE Robotics & Automation Magazine, Vol. 26, No. 4, pp. 131-135, December 2019.

http://vernon.eu/publications/19_Vernon_RAM.pdf

M. Mataric, The Robotics Primer, MIT Press, 2007. Chapter 1.

Robotics and Artificial Intelligence in Africa

By David Vernon

Artificial intelligence (AI) provides many opportunities for social and economic empowerment in developing countries. However, when one thinks of Africa, robotics does not spring immediately to mind as the most relevant application of AI, considering that the continent typically has high unemployment and fast-growing populations. Nevertheless, some countries in Africa have embraced robotics on the basis that it has an important role to play in their economic development. In this article, we explore this role and the ways in which Africa can best exploit the opportunities afforded by intelligent automation and robotics. It also highlights strategies to offset the threats posed by global factors, such as premature deindustrialization.

The Growing Impact of AI in Africa

There is an increasing awareness of the positive impact that AI will have on developing countries, including sub-Saharan Africa, in sectors such as agriculture, health care, and public and financial services [1]. AI has the potential to drive economic growth, development, and democratization, thereby reducing poverty, increasing education, supporting health-care delivery, increasing food production, expanding the capacity of the existing road infrastructure by increasing traffic flows, improving public services, and bettering the

quality of life for people with disabilities [2]. AI can empower workers at all skill levels to be more competitive [3], [4]. Specifically, it can be used to augment and enhance human skills—not to replace or displace humans—and to do so at all levels, enabling average and low-skill workers to fit better in high-performance environments and take on more complex responsibilities.

Africa's biggest economic challenge is to equip large sections of its economy with average workers who are primed to perform tasks far better than most employees are currently managing to do. In South Africa, approximately 31% of employers cannot fill their vacancies [4]. AI will make technology easier to adopt and harness [1], [4]. In the health-care sector, AI helps address the shortage of doctors through telemedicine and access to medical supplies through drone deliveries [5]. In agriculture, AI (including machine learning, remote sensing, and data analytics) has the potential to improve productivity and efficiency at all stages of the value chain, enabling small-holder farmers to increase their income through higher crop yields and greater price control, detect and precisely treat pests and diseases, monitor soil conditions and target fertilizer applications, create virtual cooperatives to aggregate crop yields, broker better prices, and exploit economies of scale. Internet of Things (IoT) platforms may offer cost-effective ways to achieve those benefits [6]. For example, Microsoft is applying its Farmbeats platform [7] in developing countries by lowering the cost associated with

densely deploying sensors, exploiting sparsely distributed sensors and aerial imagery to generate precision maps, and replacing expensive drones with smartphones attached to hand-carried, low-cost, tethered helium balloons [8].

Premature Deindustrialization

On the downside, factory and call-center work will slow as tasks are replaced by AI-enabled automation, including robots, which will add pressure to unemployment rates that are already high in developing countries, including those in Africa [5]. This will be exacerbated by growing populations, reducing opportunities still further. Africa's population is large and expanding fast: most of its people are young and urban with a median age of 19.5 years, compared to Germany (47.1), the United States (38.1), and China (37.7), and the youth population is set to reach 225 million by 2055 [5]. Kenya, Nigeria, and South Africa, for example, are projected to have approximately 5.5%, 8.5%, and 12.5%, respectively, of their workforce displaced by automation [9]. A report by the Oxford Martin School at the University of Oxford, United Kingdom, and Citigroup, New York, summarizes the situation in Africa in stark terms [10]:

In most of sub-Saharan Africa, the manufacturing share of output has persistently declined over the past 25 years. The share of jobs in manufacturing is even smaller: just over 6% of all jobs. This figure barely changed over the course of the three decades

Digital Object Identifier 10.1109/MRA.2019.2946107
Date of current version: 11 December 2019

Videos

Atlas (0:30):	https://robots.ieee.org/robots/atlas2016/?gallery=video5
iCub (2:40):	https://robots.ieee.org/robots/icub/?gallery=video1
Roomba (1:30):	https://robots.ieee.org/robots/roomba/?gallery=video2
Turtlebot (1:30):	https://robots.ieee.org/robots/turtlebot/?gallery=video1
Zipline (0:06):	http://www.vernon.eu/videos/Zipline_hero.mp4
Zipline (1:09):	https://www.youtube.com/watch?v=QWglZKVP26c
Zipline (0:15):	http://www.vernon.eu/videos/Zipline_drop.mp4
Zipline (11:44):	https://www.youtube.com/watch?v=jEbRVNxL44c
Picker Robots (0:15):	https://robots.ieee.org/robots/invia/?gallery=video5
Sawyer (0:30):	https://robots.ieee.org/robots/sawyer/?gallery=video1
Meca (1:15):	https://robots.ieee.org/robots/meca500/?gallery=video1
Shadow Hand (3:00):	https://robots.ieee.org/robots/shadow/?gallery=video4
Spot (2:00):	https://robots.ieee.org/robots/spotmini/?gallery=video1
Salamandra (0:43):	https://robots.ieee.org/robots/salamandra/?gallery=video4