# Introduction to Cognitive Robotics

Module 9: The CRAM Plan Language

Lecture 1: Fluents, concurrency, reasoning, exception handling

David Vernon
Carnegie Mellon University Africa

www.vernon.eu

# The CRAM Language

Based on CRAM documentation http://cram-system.org/doc

## The CRAM Language

The CRAM language is an extension of Lisp

- Recall Lisp's natural extensibility and suitability for task-specific programming languages ...
   the CRAM language is an extension of Lisp
- Exploiting macros and functions
- Making heavy use of the operating system's multi-threading, especially for one of the key extensions: fluents

## The CRAM Language

#### The CRAM language is an extension of Lisp

- The following provides an overview of a small subset of these extensions
- mainly to allow you to understand
  - The Beginner Tutorials
  - The detailed explanation of the pick-and-place CRAM plan example
    - The "Zero prerequisites demo tutorial: Simple fetch and place" http://cram-system.org/tutorials/demo/fetch\_and\_place)
    - The "How to write a simple mobile manipulation plan" intermediate tutorial http://cram-system.org/tutorials/intermediate/simple mobile manipulation plan
- For more details, see the CRAM language resources at the end

- A fluent is a proxy object for some Common Lisp object
- It is used as a variable that allows a thread to effectively monitor and act on a change in value of a Lisp object

The current thread blocks until the value of the fluent changes

```
(whenever fluent)
```

- Iteratively repeats the body except when (value fluent) is nil before a new iteration
- If it is nil, the thread blocks until the fluent becomes true
- Unless return is called explicitly, the whenever form never terminates:
   it either repeatedly evaluates the body or blocks

- A fluent is created with the function make-fluent
- The fluent is accessed through the reader function value
- A fluent can be set as follows
   (setf (value fluent) <value>)
- A fluent can be pulsed with (pulse fluent)

#### 

Block until the value is not nil

#### Example

```
(let ((fl (make-fluent :test-fluent :value nil)))
         (spawn-perception fl)
         (whenever (fl)
            (when (eq (value fl :done))]
                                             return when the fluent value is : done
              (return-from whenever))
            (format t "Received value: ~a~%" (value fl))))
Block until the value is not nil
otherwise, execute body repeatedly
                                           Repeatedly print the value of the fluent
                                           If you only want to print the value when it changes use
                                            (whenever ((pulsed fl))
                                               . . . )
```

### Fluent Networks

- Fluents can be combined to create fluent networks
- A fluent network updates is value whenever one of the constituent fluents changes its value
- Combination is effected using (overloaded) relational, arithmetic, and logical operators

Recall the native and returns the first non-nil value fl-and returns a fluent containing T or nil

#### Fluent Pulses

- Whenever the value of a fluent is set to a different value, the fluent is pulsed automatically
- You can also pulse the fluent (without changing the value) with the pulse method
- To construct a fluent network that reacts if its constituent fluents are pulsed, use the pulsed combinator

```
e.g. (wait-for (pulsed fluent))
```

#### Fluent Pulses

- whenever in combination with a pulse works like an infinite loop waiting for a
  pulse and then executing the body when the pulse occurs
- What happens if a fluent is pulsed when the body is being executed, i.e. what happens if there is a "missed" pulse?
- The (pulsed fl) form has three optional keywords to specify how pulses that occur during the execution of the body of a whenever are to be handled

#### Fluent Pulses

```
(pulsed fl :handle-missed-pulses :once)
```

Any number of missed pulses cause cause exactly one additional execution of the whenever body

```
(pulsed fl :handle-missed-pulses :never)
```

Missed pulses don't cause cause any additional execution of the whenever body

```
(pulsed fl :handle-missed-pulses :always)
```

The number of iterations of the whenever body exactly matches the number of missed pulses: the whenever body gets executed for every value change

### **Definition of Functions**

• When defining functions to implement CRAM plans, use def-cram-function instead of defun

• def-cram-function uses the same syntax as defun

## Top-level

CRAM language forms must be executed in a top-level environment:

```
(top-level
    ...
)
```

Alternatively, you can define a plan using

```
(def-top-level-plan
    ...
)
```

This contains an implicit top-level form

- Functions can be called sequentially or concurrently
- Sequential execution

```
(seq ...
```

- Execute forms sequentially
- Equivalent to progn
- Fails if one of the component sub-forms fails
- Succeeds when all of the component sub-forms succeed

- Functions can be called sequentially or concurrently
- Sequential execution

- Execute forms sequentially
- Fails if all of the component sub-forms fail
- Succeeds if one of the component sub-forms succeeds

- Functions can be called sequentially or concurrently
- Parallel execution

```
(par
...
```

- Execute forms in parallel
- Fails if one of the component forms fails
- Succeeds when all the component sub-forms succeed

- Functions can be called sequentially or concurrently
- Parallel execution

```
(pursue ...
```

- Execute forms in parallel
- Fails if one of the component forms fails
- Succeeds when one the component sub-forms succeeds
- All other forms are evaporated (abandoned) when one form succeeds

- Functions can be called sequentially or concurrently
- Parallel execution

```
(pursue
  (wait-for (robot-at waypoint))
  (loop do
      (update-navigation-cmd waypoint)
      (sleep 0.1))
```

- Terminates successfully when the robot is at the waypoint
- Navigation commands to approach the waypoint are sent to the robot repeatedly

- Functions can be called sequentially or concurrently
- Parallel execution

```
(try-all ...)
```

- Execute forms in parallel
- Fails if all of the component forms fail
- Succeeds when one the component sub-forms succeeds

## **Exception Handling**

Plan failures are generated and thrown using (fail <failure type>)

```
(handle-failure ...)
```

Wraps function calls so that, if a failure occurs, failure handling is executed

### **Exception Handling**

• The cram\_reasoning package contains a full-featured Prolog interpreter (written in Lisp)

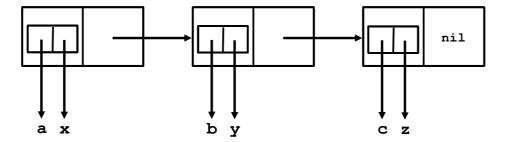
• The interpreter return a lazy list of solutions

Solutions are generated on demand by accessing the element of the list

```
(prolog ...) executes the interpreter and proves a goal
CRS> (prolog '(member ?x (a b c)))
(((?X . A)) . #S(CRAM-UTILITIES::LAZY-CONS-ELEM :GENERATOR ...)
           First solution of the lazy list result; this solution is a tuple (i.e. a cons) with variable name in the car
           and the value in the cdr
               force expansion of the lazy list
CRS> (force-ll (prolog '(member ?x (a b c))))
(((?X . A)) ((?X . B)) ((?X . C)))
          List of all three conses
```

### Recall: Assoc-lists

- Conses can also be used to represent mappings
- A list of conses is called an assoc-list or alist



### Two ways to define a predicate

- use a fact-group
- Implement a Lisp function to get the current bindings and the predicate's parameters,
   and return a list of binding sets

```
(def-fact-group name (public-predicate*) fact-definition)
```

- Defines a fact group
- The public-predicate field declares which predicates can be defined in other factgroups
- Predicates are defined using <-</li>

## CRAM Language Resources

CRAM Language http://cram-system.org/doc/package/cram\_language

CRAM Reasoning http://cram-system.org/doc/package/cram\_reasoning

## **Background Reading**

G. Kazhoyan, Lecture notes: Robot Programming with Lisp 7. Coordinate Transformations, TF, ActionLib, slides 5-8. https://ai.uni-bremen.de/ media/teaching/7 more ros.pdf

T. Rittweiler, CRAM – Design and Implementation of a Reactive Plan Language, Bachelor Thesis, Technical University of Munich, 2010.

https://common-lisp.net/~trittweiler/bachelor-thesis.pdf